

# Intelligent Weed Control Systems



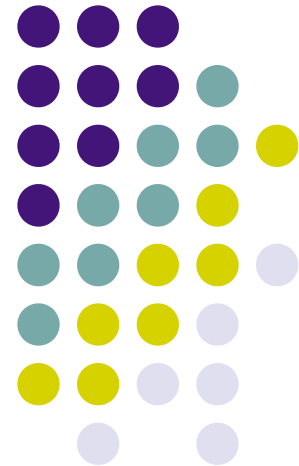
Manuel Pérez-Ruiz

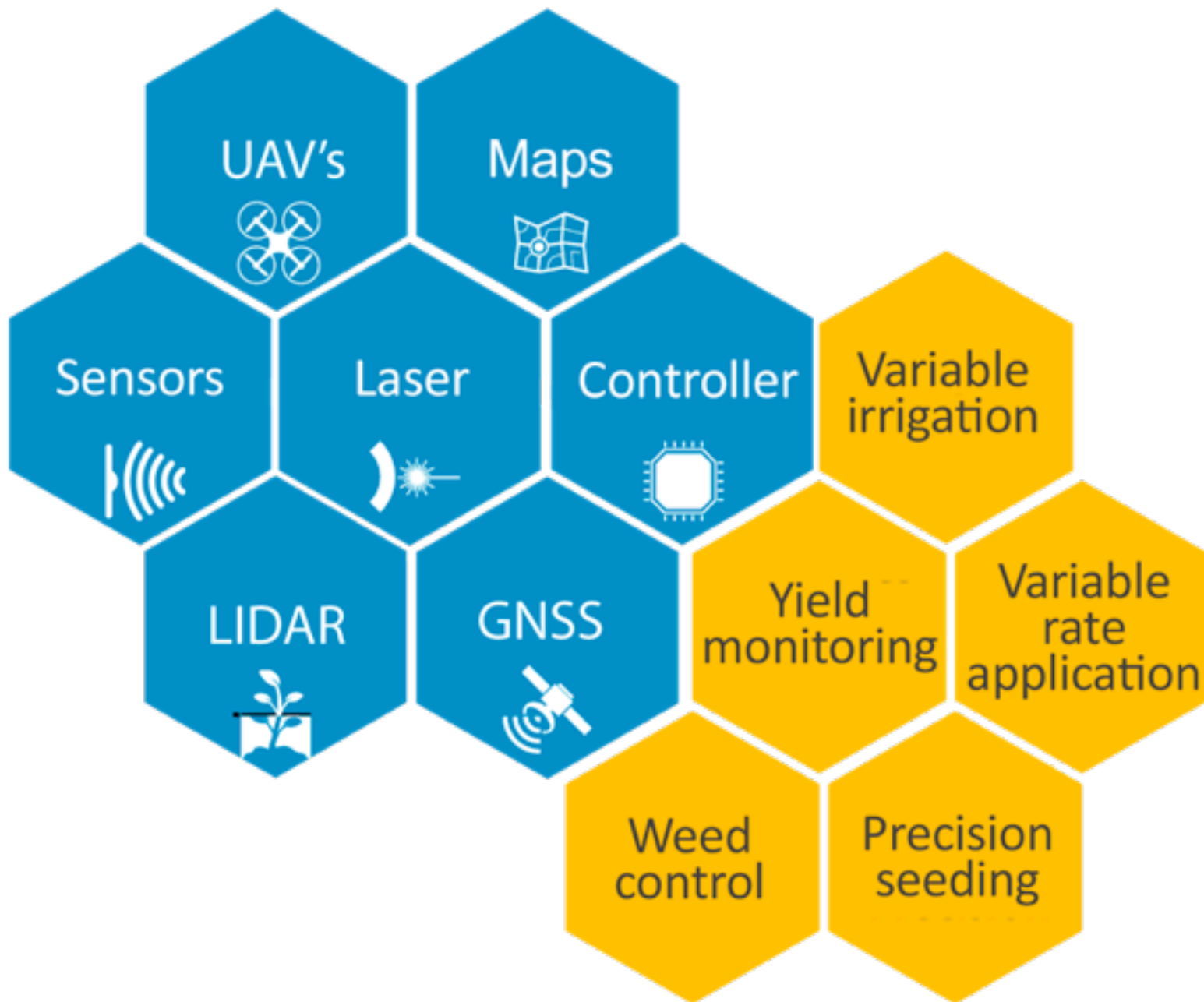
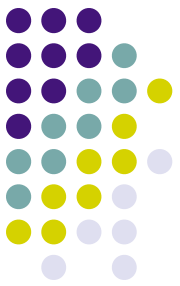
Universidad de Sevilla

Dpto. de Ingeniería Aeroespacial y Mecánica de Fluidos  
ETSIA, Área de Ingeniería Agroforestal

Universidad de Sevilla

[manuelperez@us.es](mailto:manuelperez@us.es)





The farmer of the year 2031 works at his large flat-panel television (1931).



*The Country  
Gentleman magazine*





*che colgono olive verdi su piazze in una sola pianta 1896, (Fototeca Georgofili - Fondo R.E.D.A.)*

**From Green Revolution (increased agricultural production) to  
Smart Agriculture (sustainability)**

**From Fossil generation to  
Bio and Digital generation**

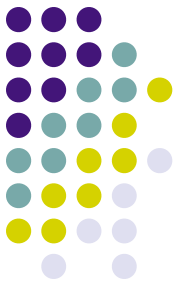




# Unsustainable weed control:



# Unsustainable weed control:



## California 2014



## Sevilla 2015

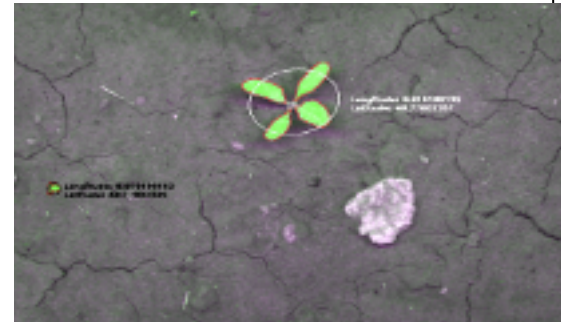
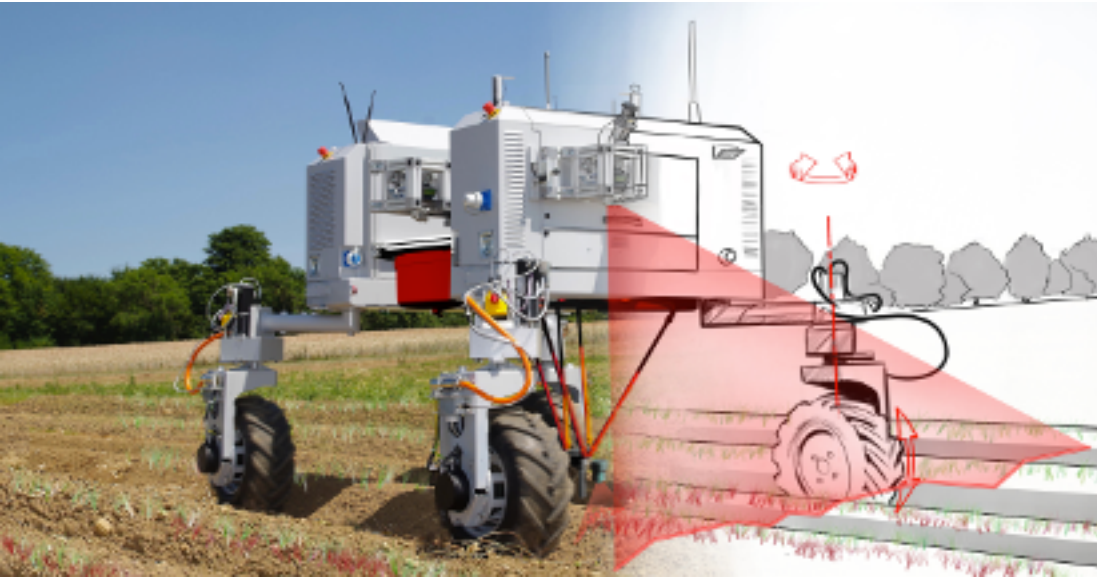
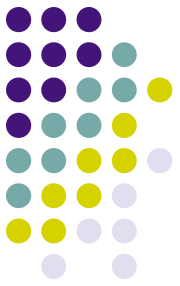


### ¿Precision Farming?

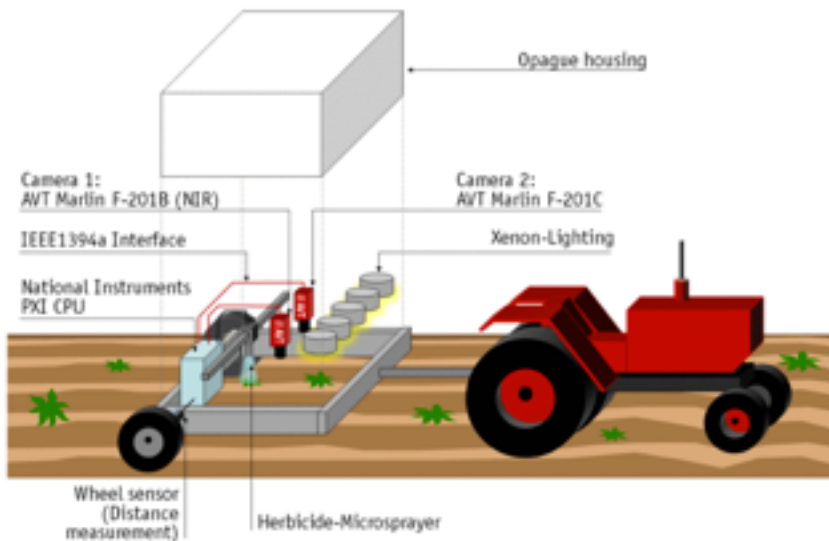
**“apply the right treatment in the right place at the right time”  
(Gebbers and Adamchuk, 2010)**



# What is working.....?



## Vision based, mechanical weed control

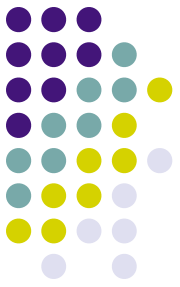


## Mechanical stamping actuator



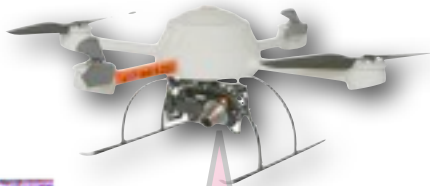


# Monitoring tools

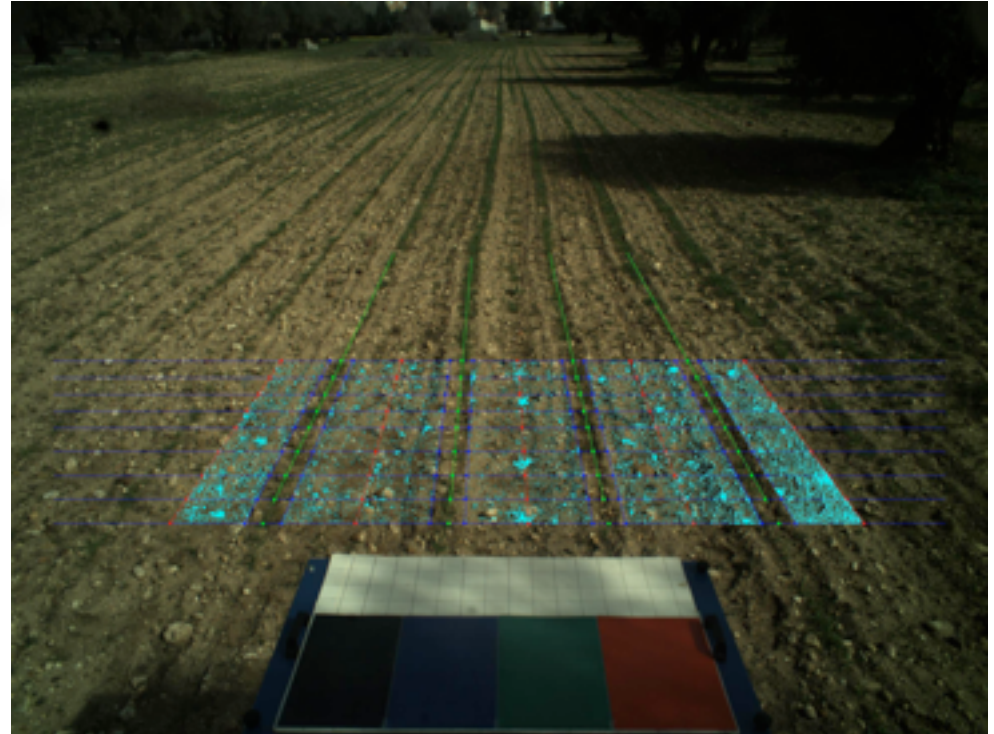


## Prescription maps (weed infestation map)

Peña et al.



## Vision Technology

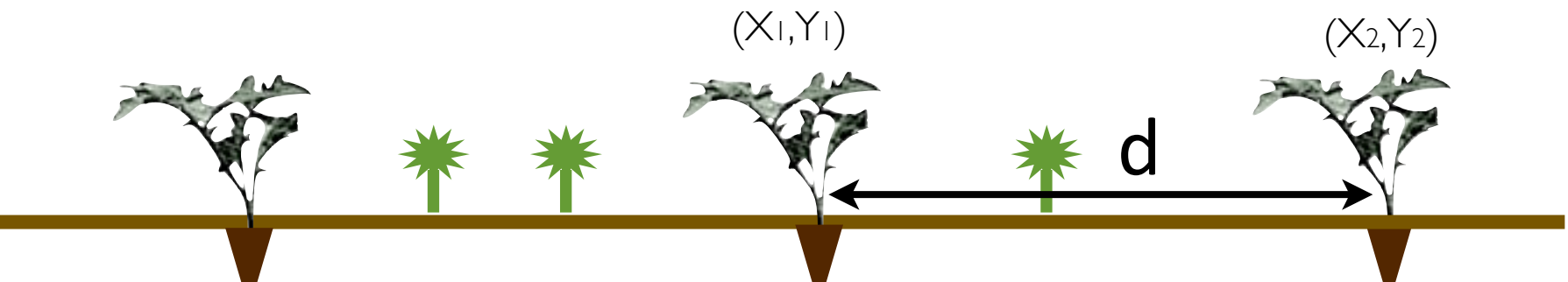
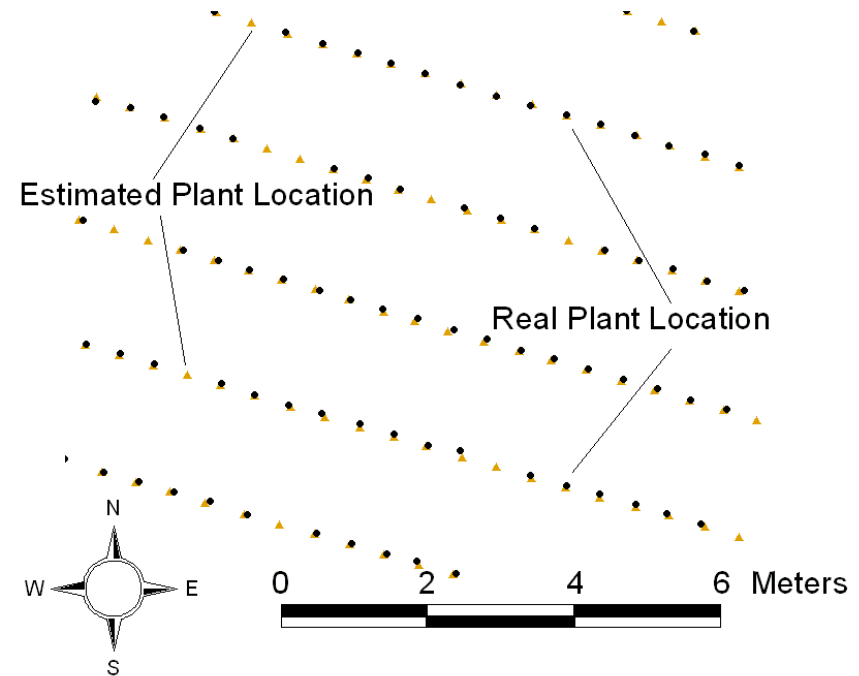
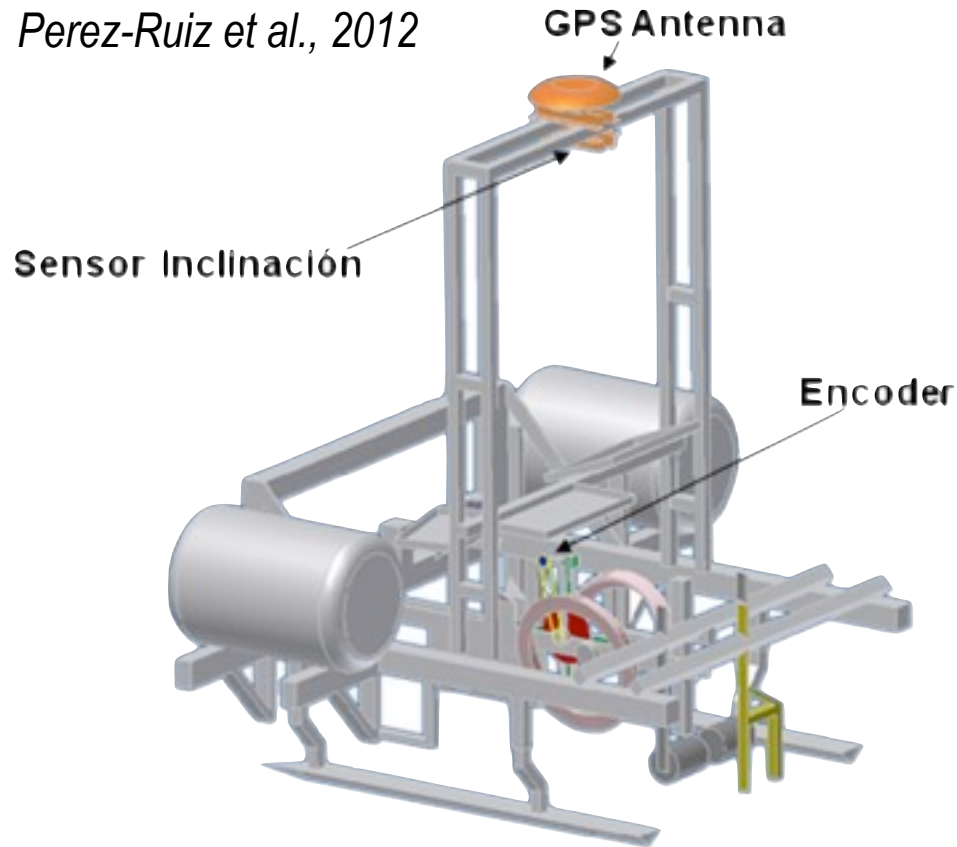
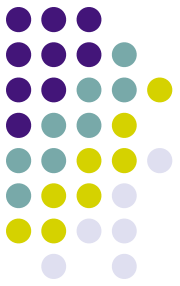


# Monitoring tools

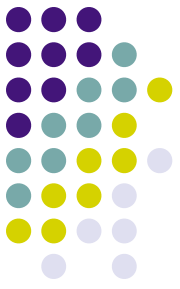
*Sun et al., 2010*

*Perez-Ruiz et al., 2012*

## GNSS & Odometry

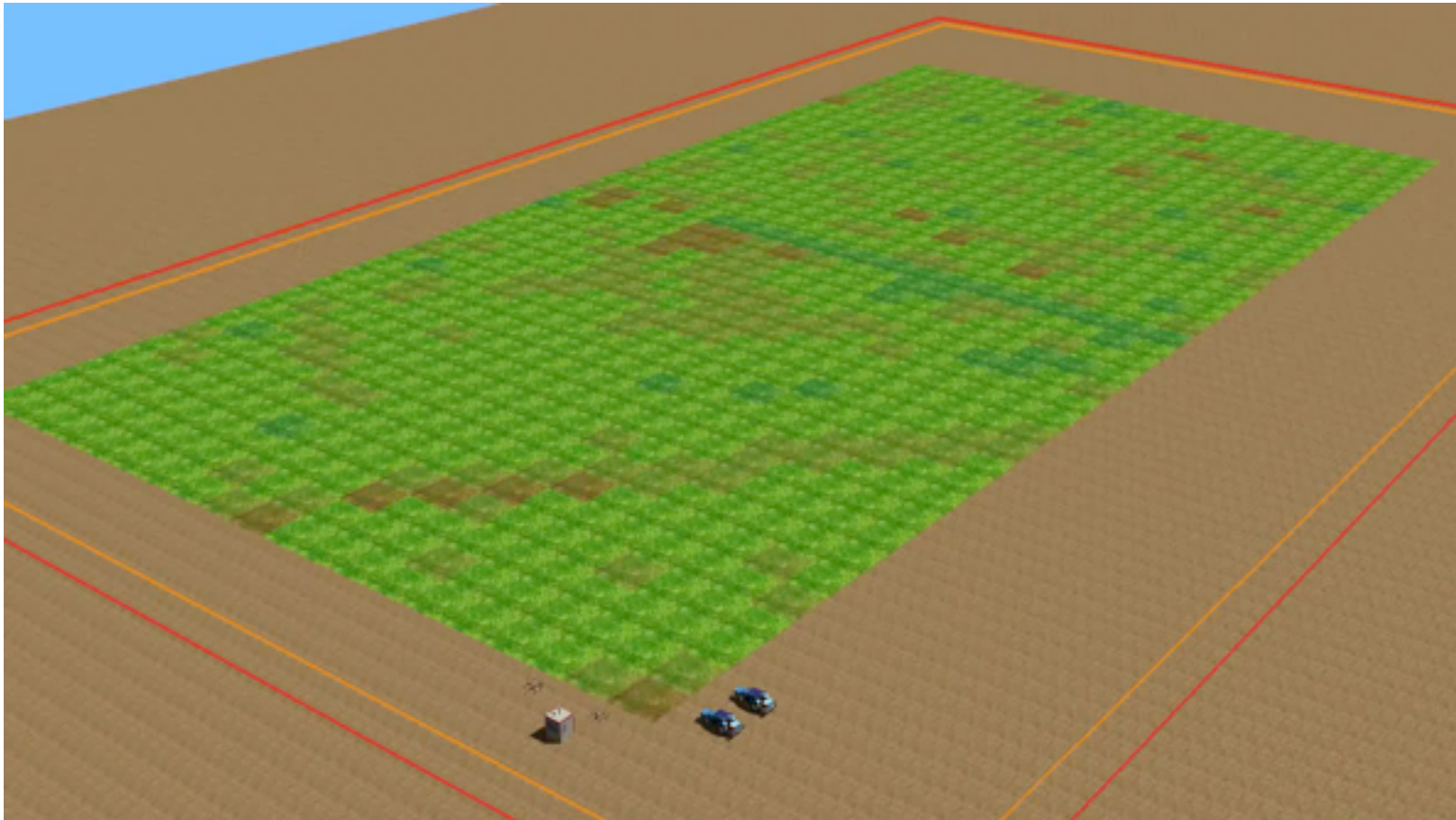


# Precision spray application system



## Robot Fleets For Highly Effective Agriculture and Forestry Management (RHEA)-2014

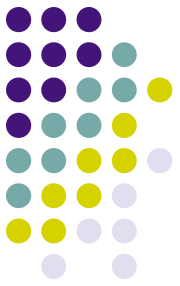
Accuracy  
Computer  
Robot  
**RHEA**  
Weed  
Mission  
Sensing  
Mapping  
UAV  
Vision  
RealTime  
Strategies



RHEA-Simulation



# Precision spray application system

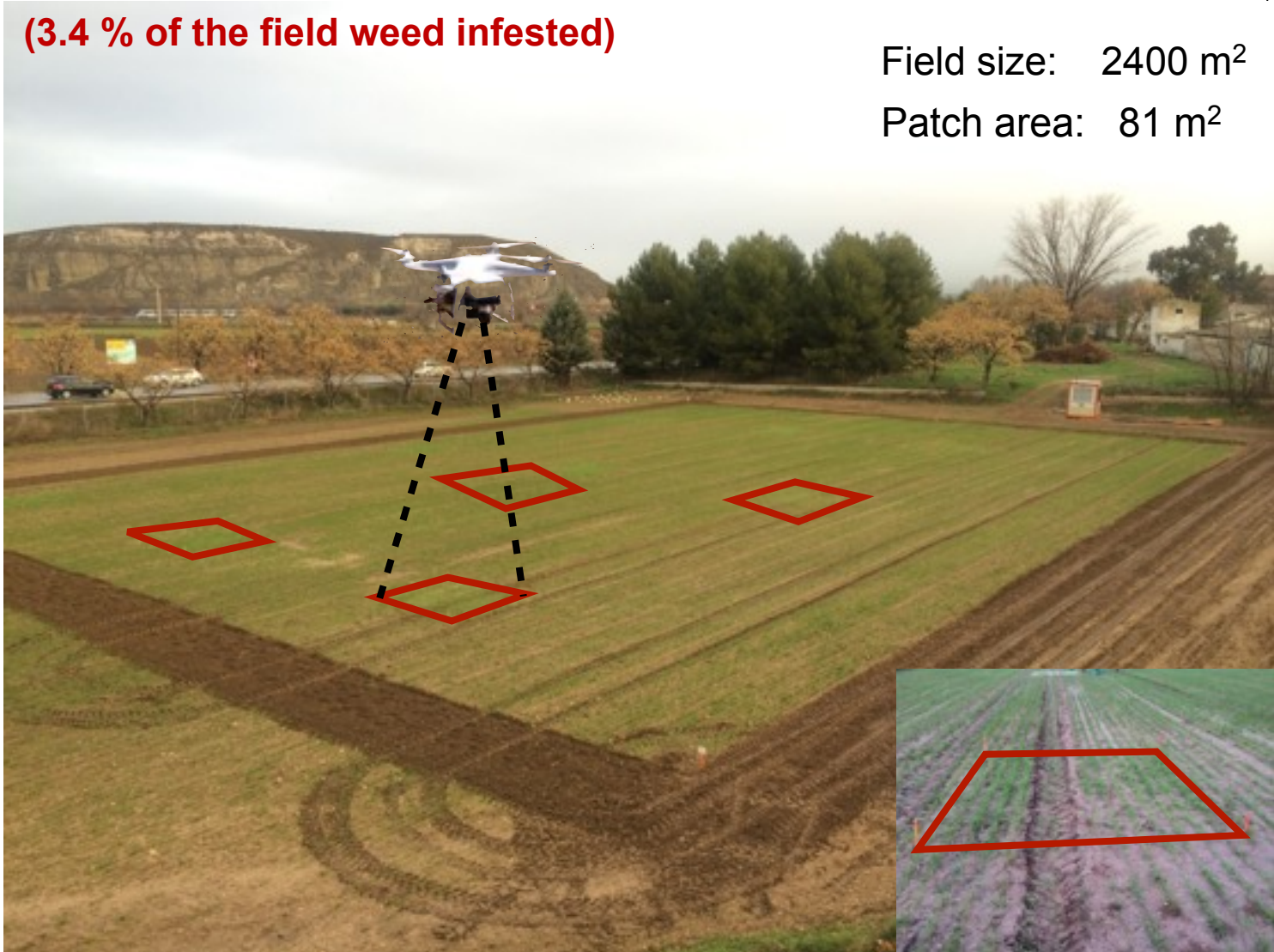


## UAV weed detection

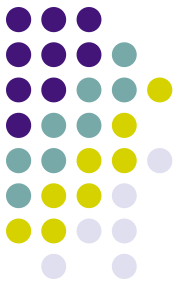
**(3.4 % of the field weed infested)**

Field size: 2400 m<sup>2</sup>

Patch area: 81 m<sup>2</sup>



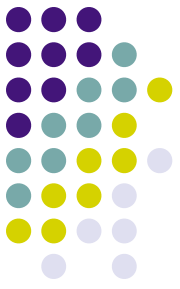
# Precision spray application system



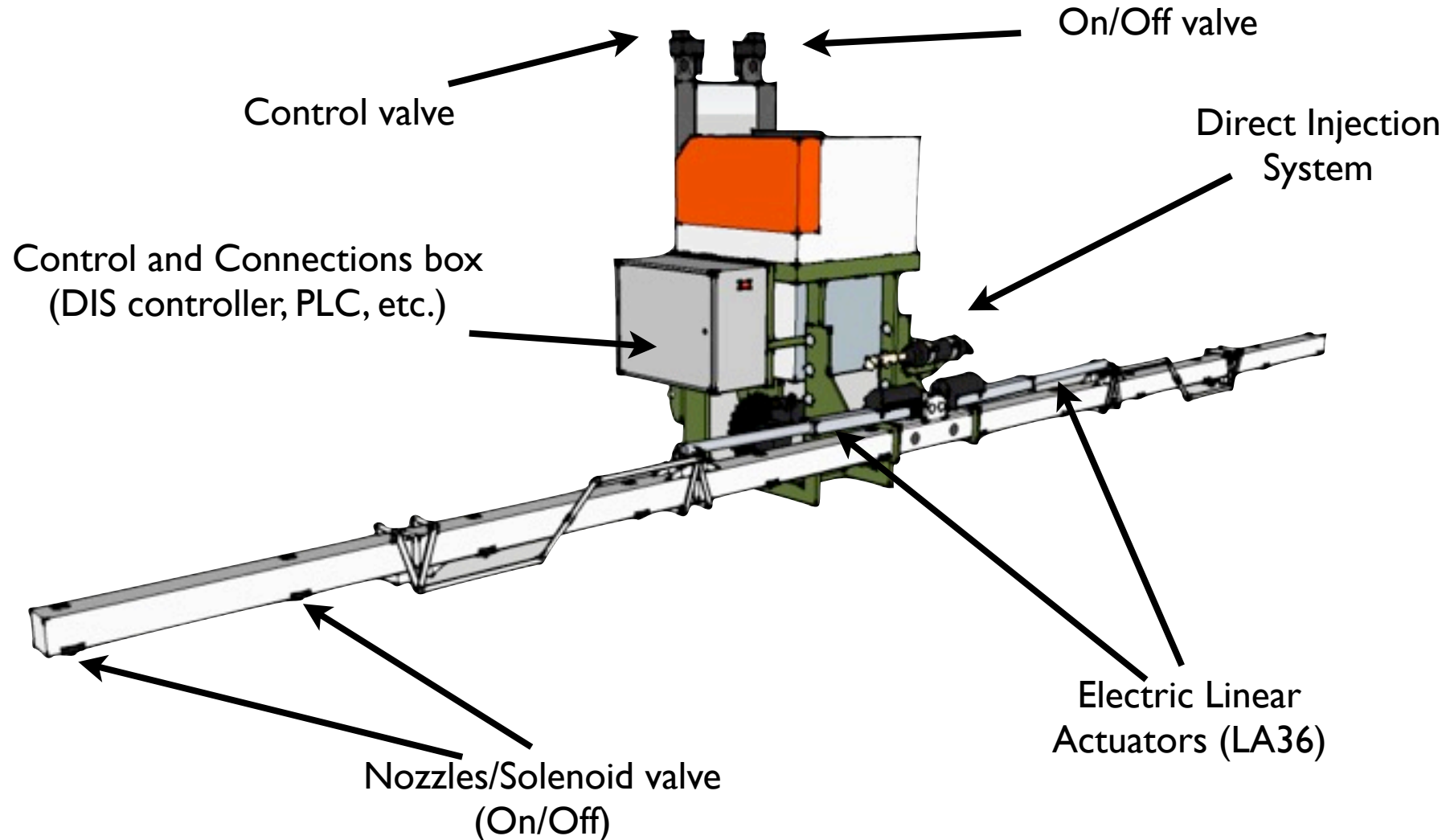
## Autonomous tractor



# Precision spray application system

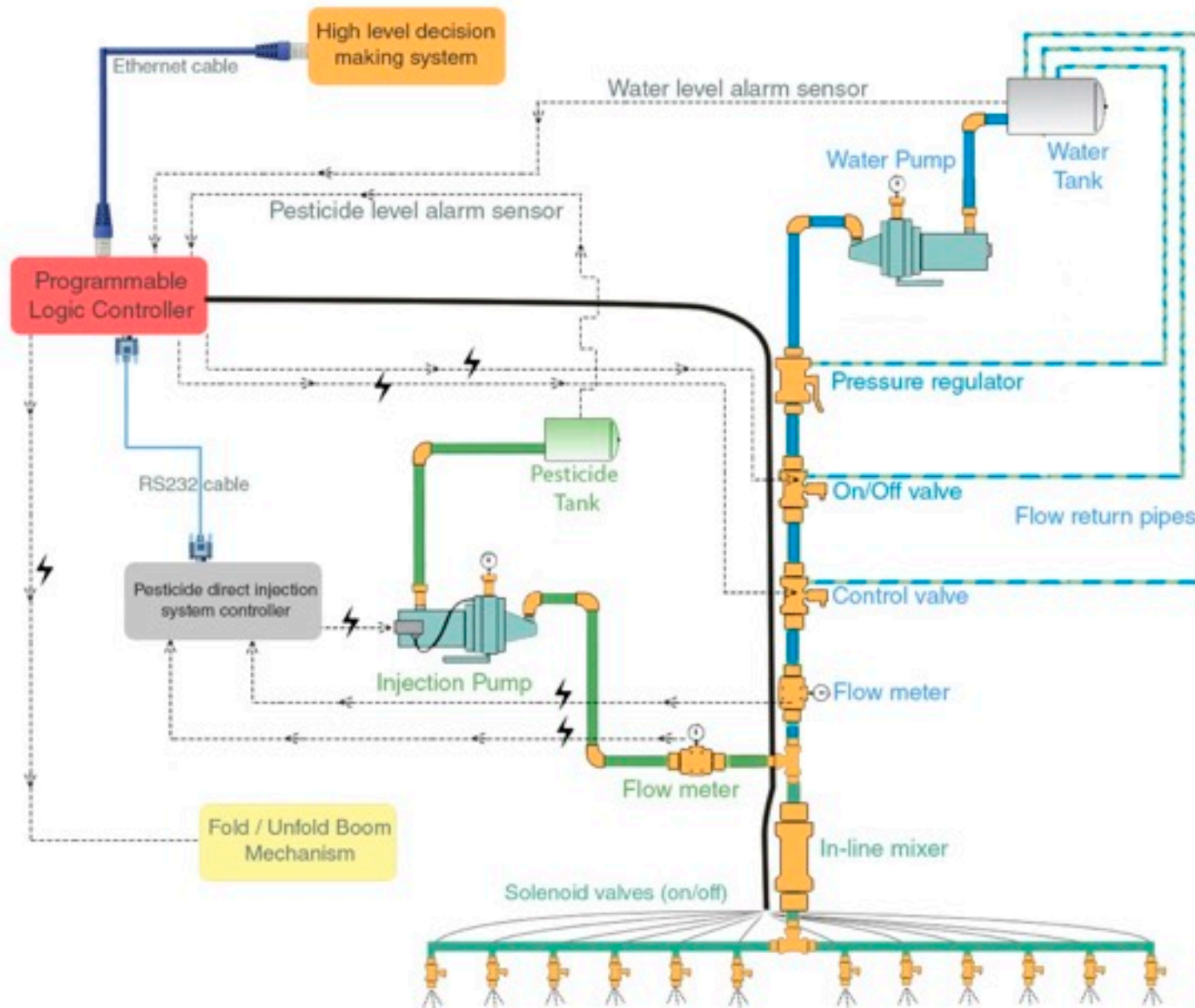
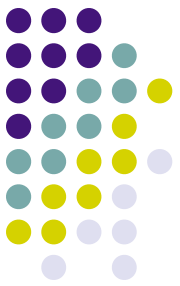


## Intelligent sprayer

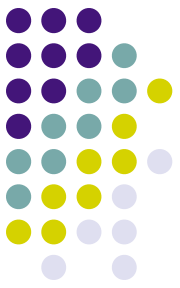




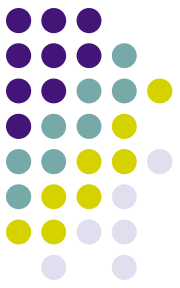
# Precision spray application system



# Precision spray application system

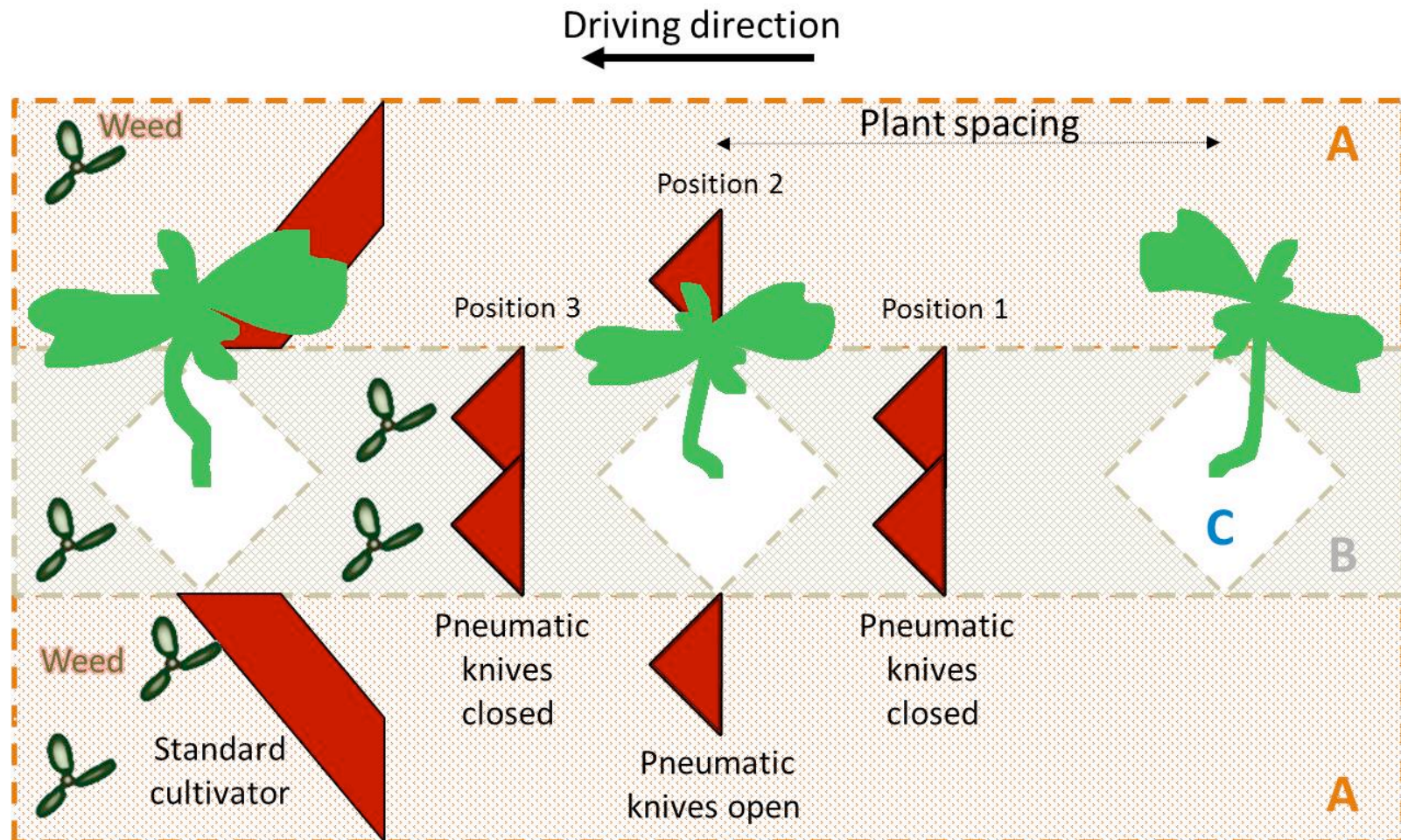






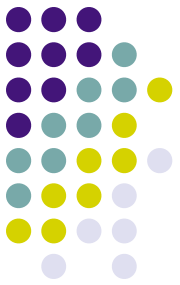
# GNSS-based mechanized weed control

Three weed control zones have been defined in relationship to the crop plant



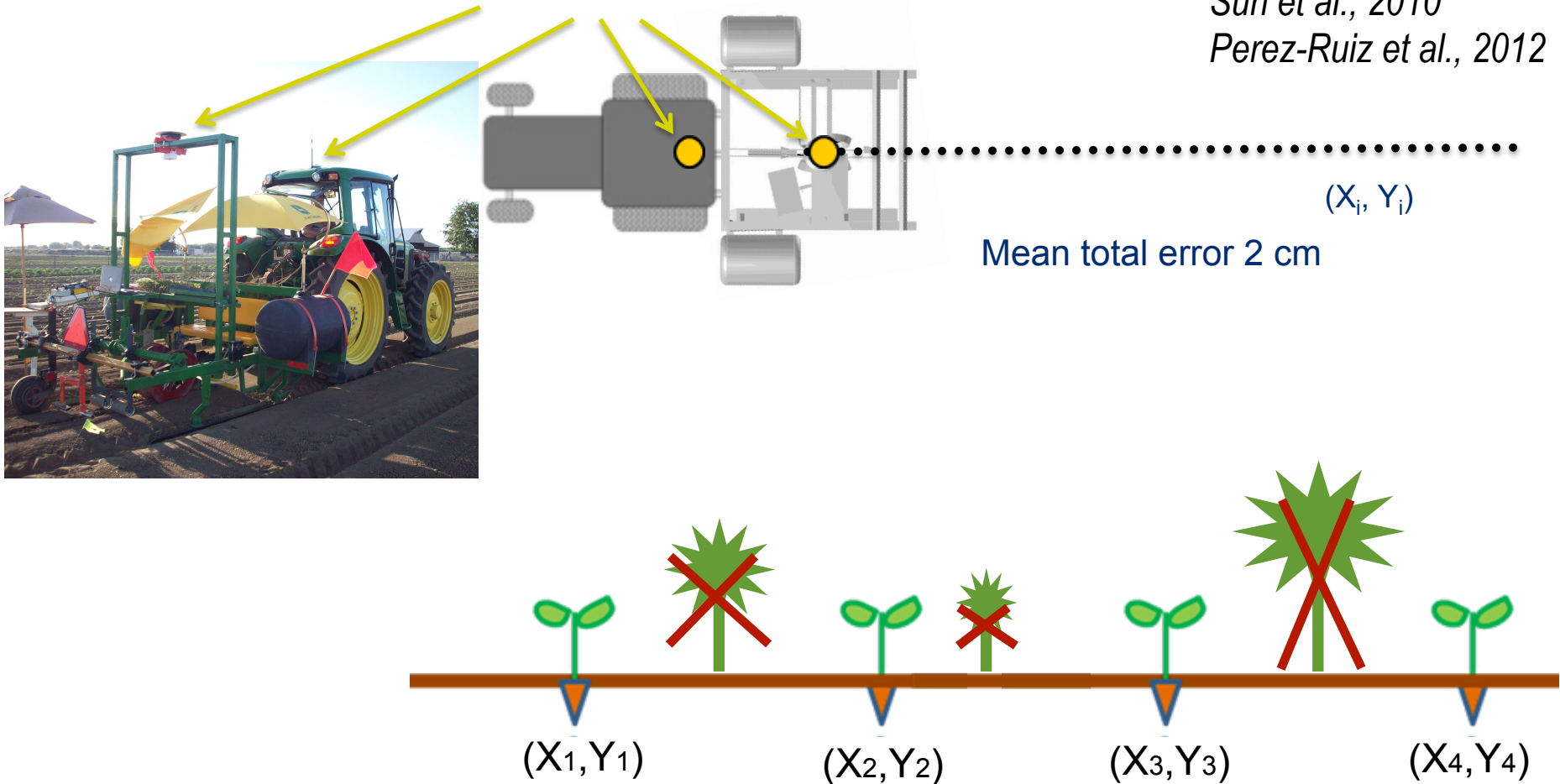


# GNSS-based mechanized weed control

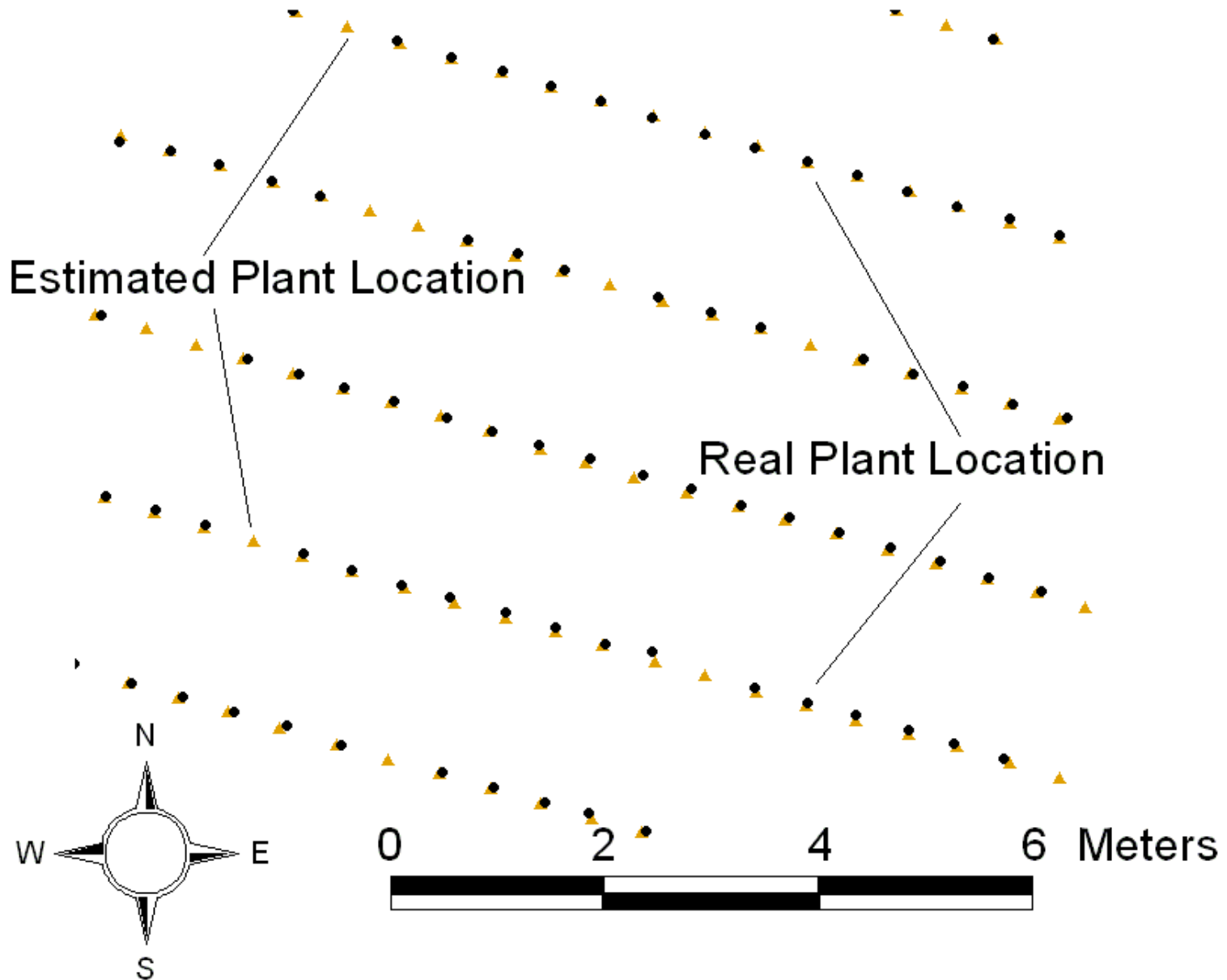


RTK-GPS antenna

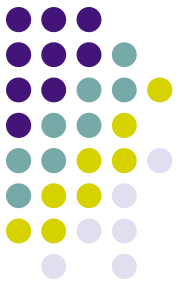
*Sun et al., 2010*  
*Perez-Ruiz et al., 2012*



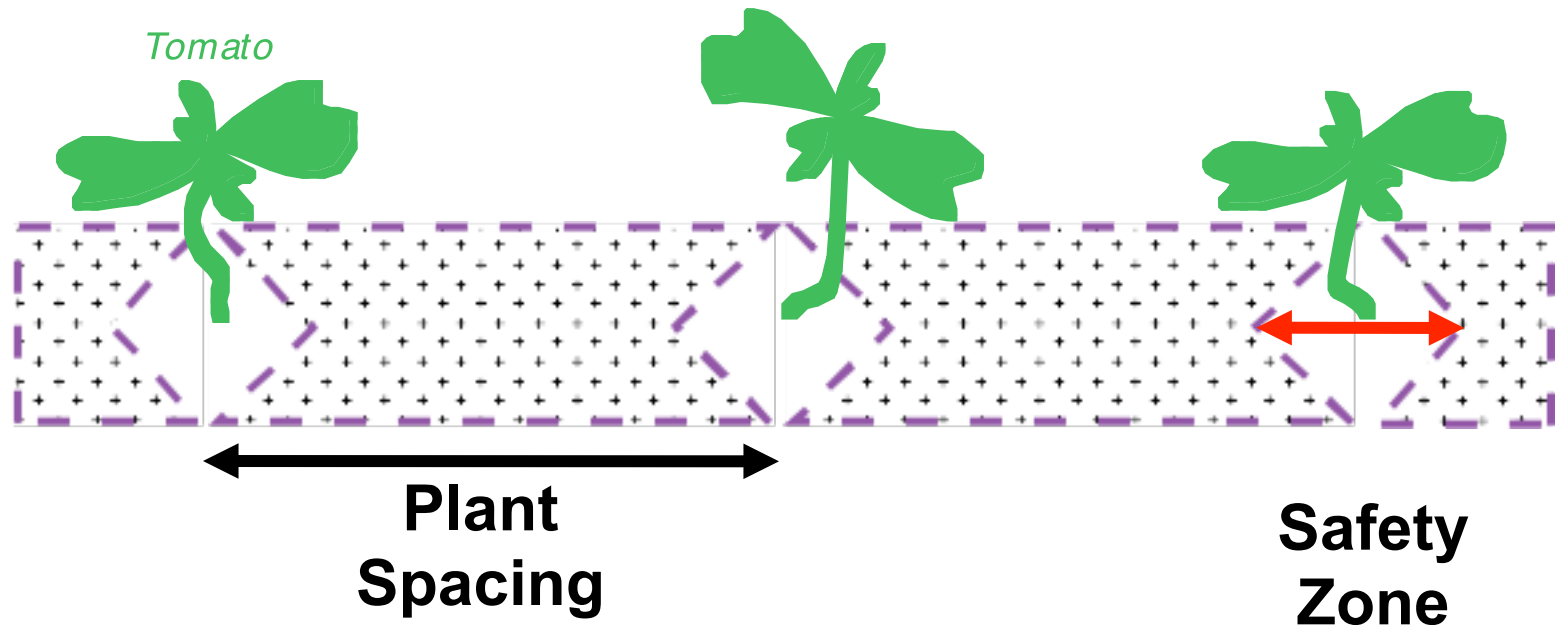
# Crop geoposition map



# Odometry- based mechanized weed control



➡ Operator enters plant spacing and the size of the safety zone

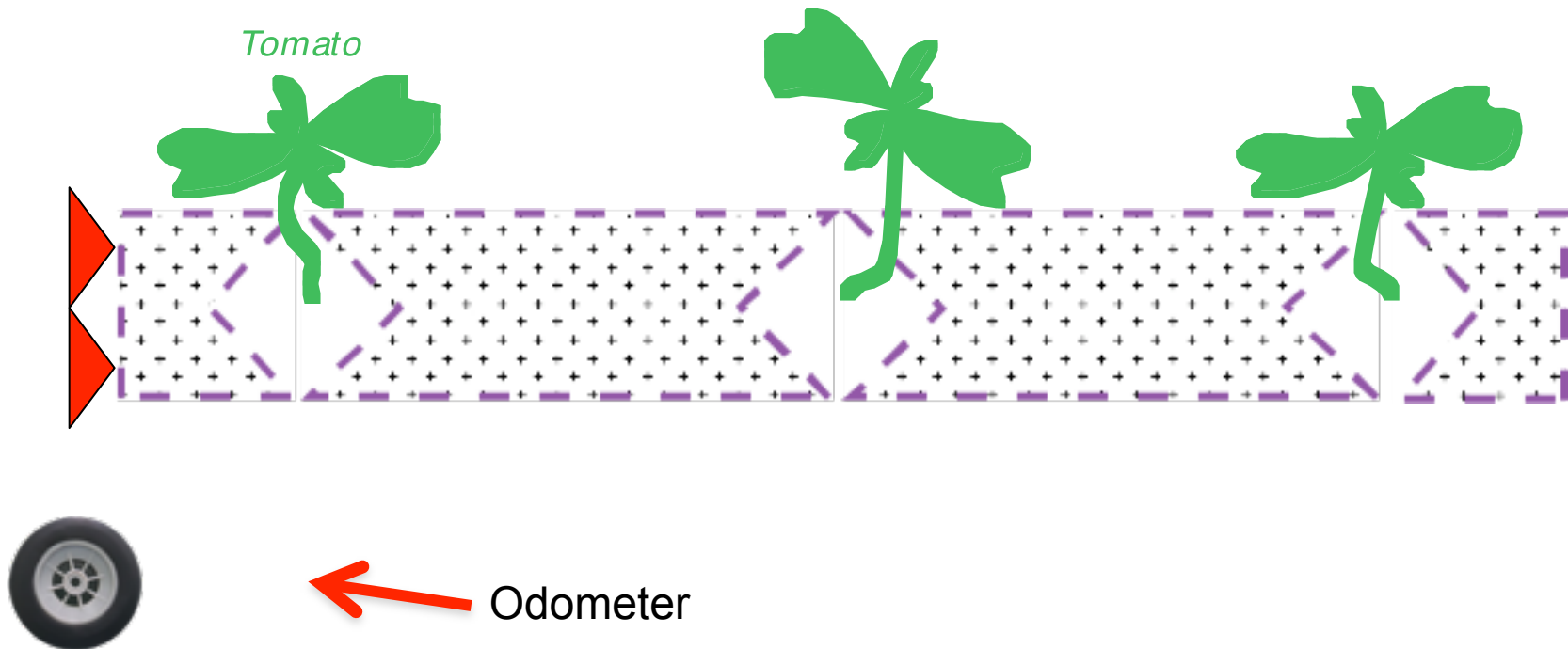




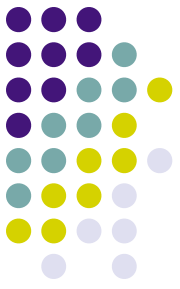
# Odometry- based mechanized weed control



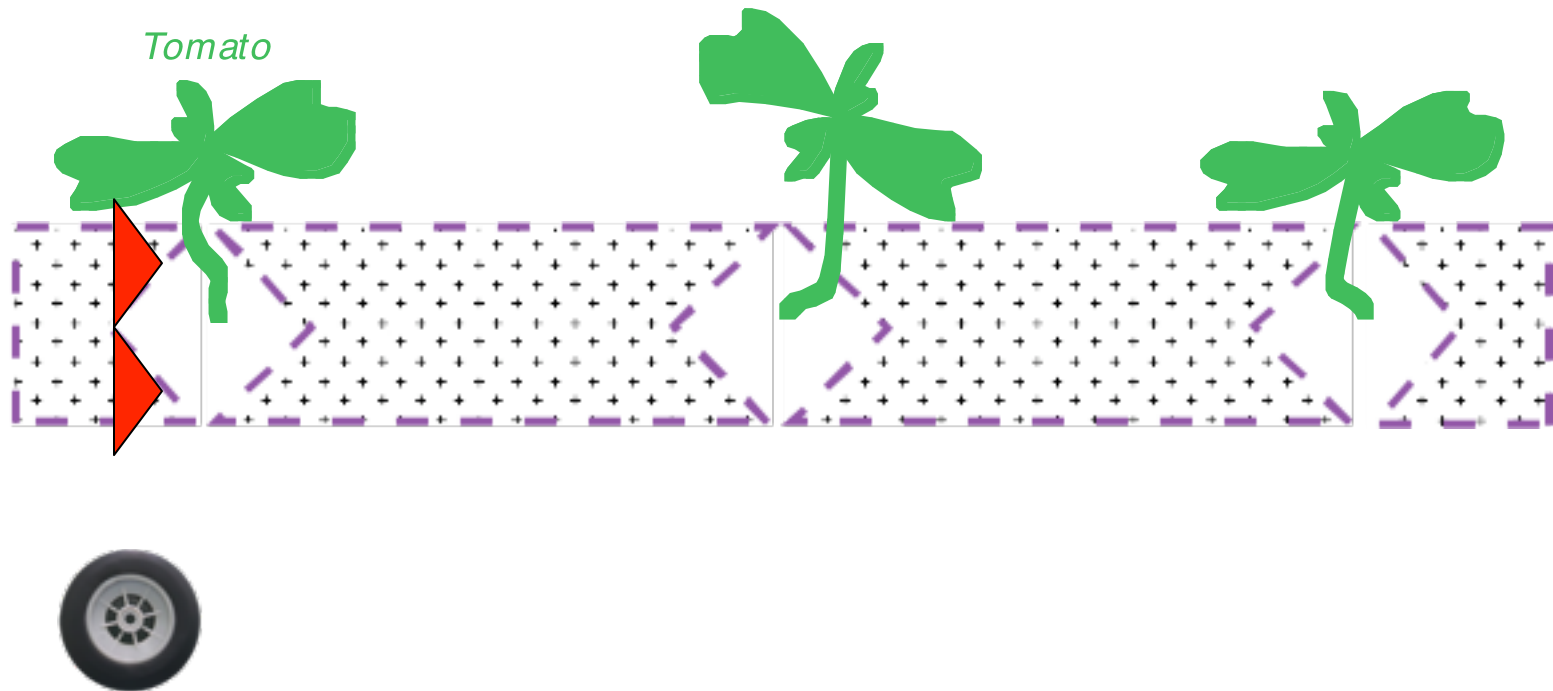
➡ Low cost (\$30) controller monitors the odometer during cultivation



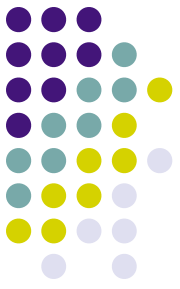
# Odometry- based mechanized weed control



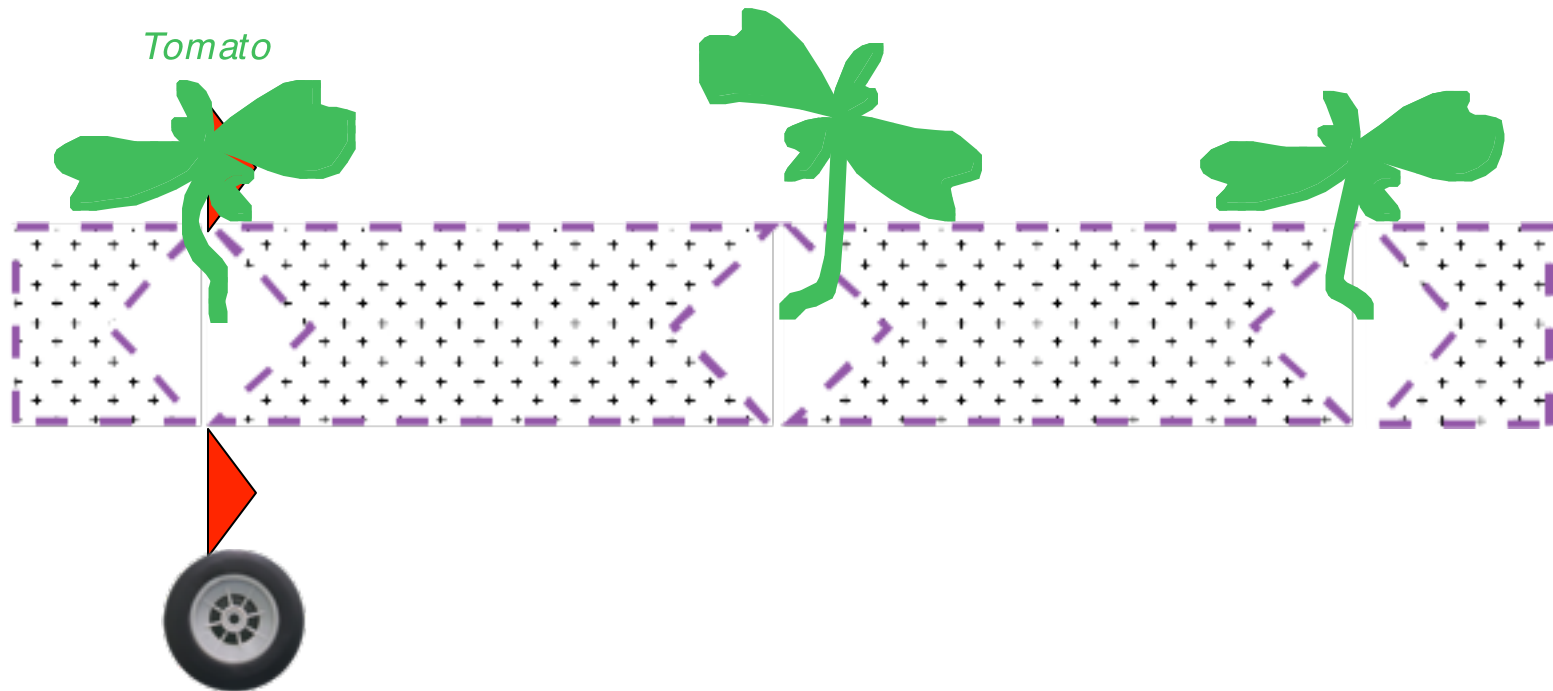
➡ At the safety zone, the controller opens the knives



# Odometry- based mechanized weed control



➡ Closing the knives as it passes the plant

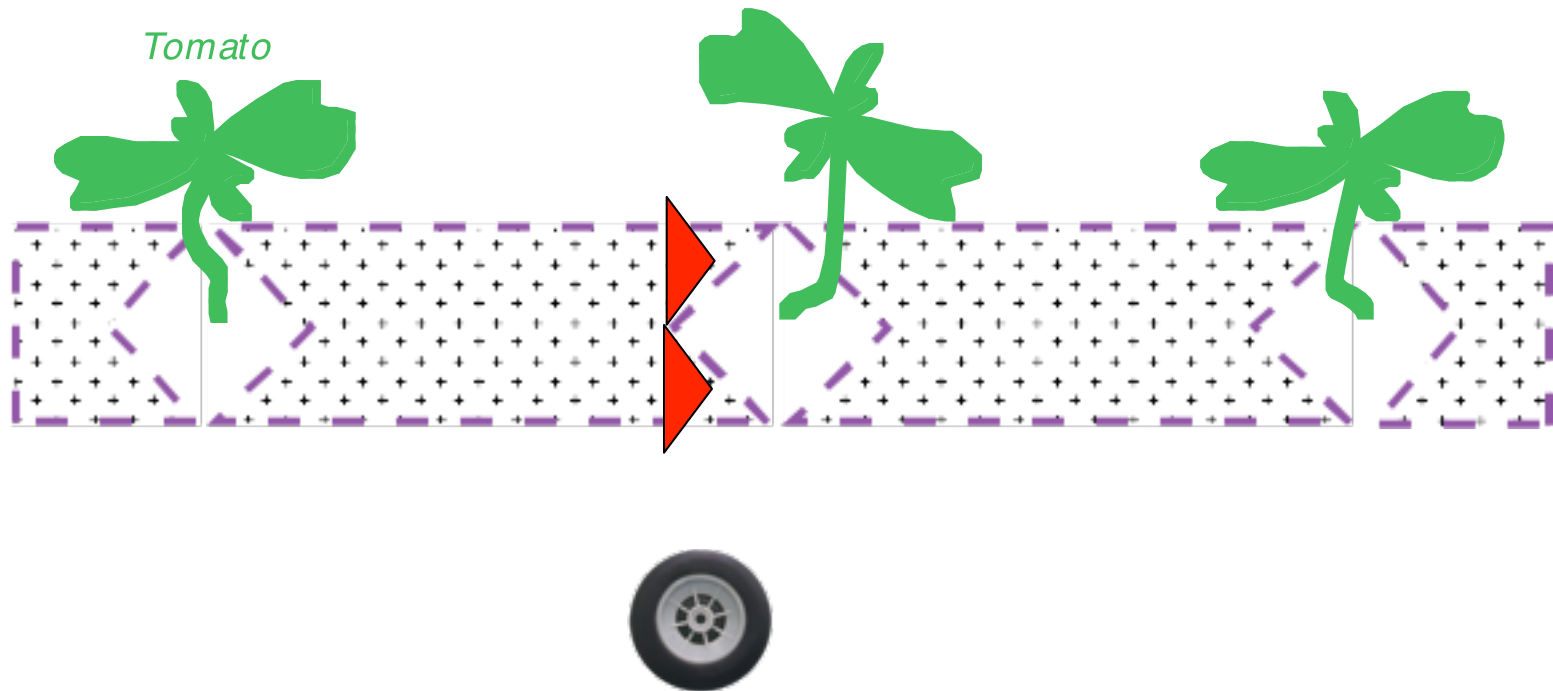




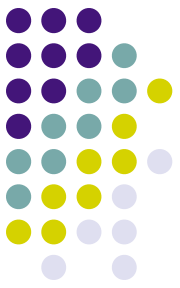
# Odometry- based mechanized weed control



➡ The pattern repeats, without operator intervention



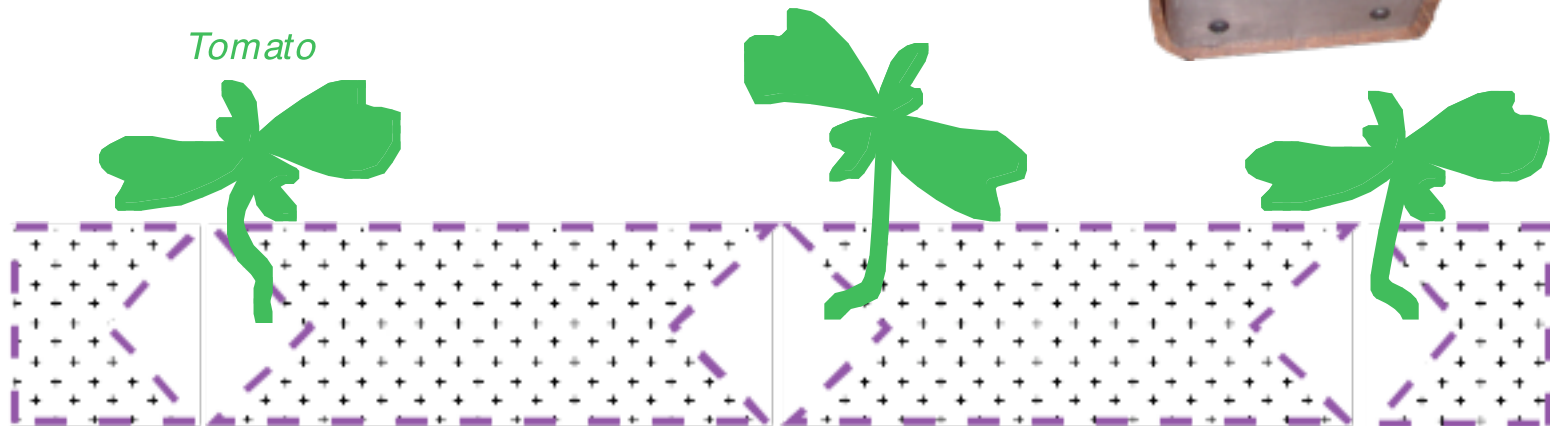
# Odometry- based mechanized weed control



➡ Periodically, the operator can shift the pattern, if needed

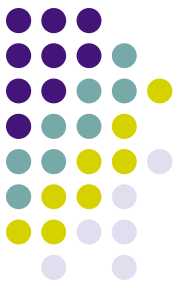


Shift wheel



Pattern Shift

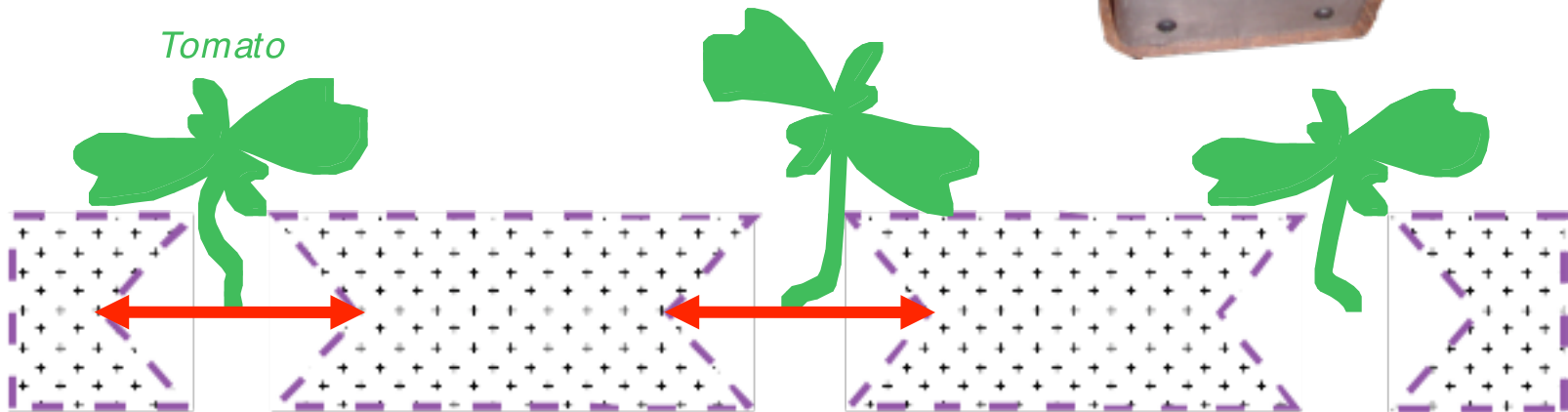
# Odometry- based mechanized weed control



➡ Or change the size of the safety zone



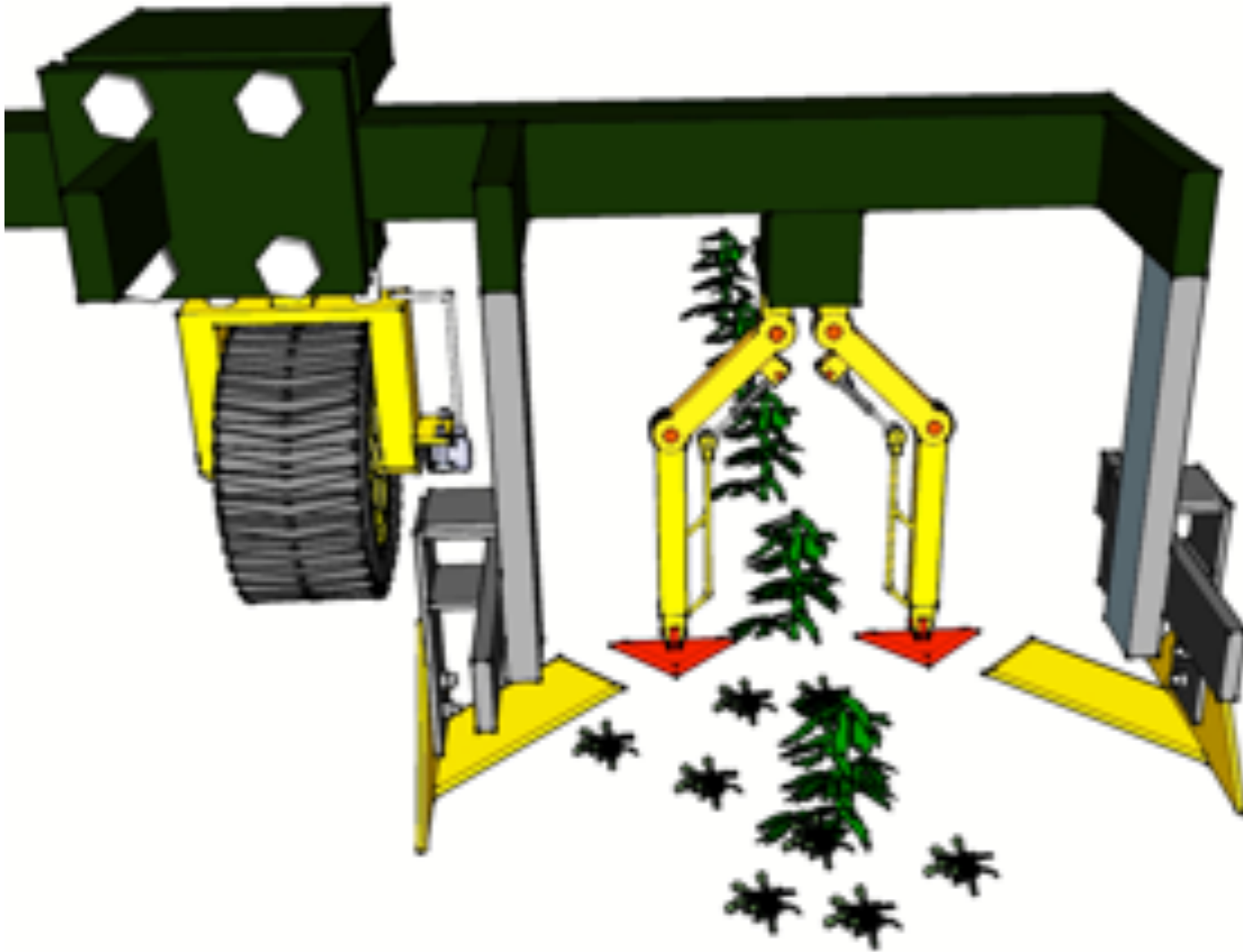
Safety  
zone  
wheel



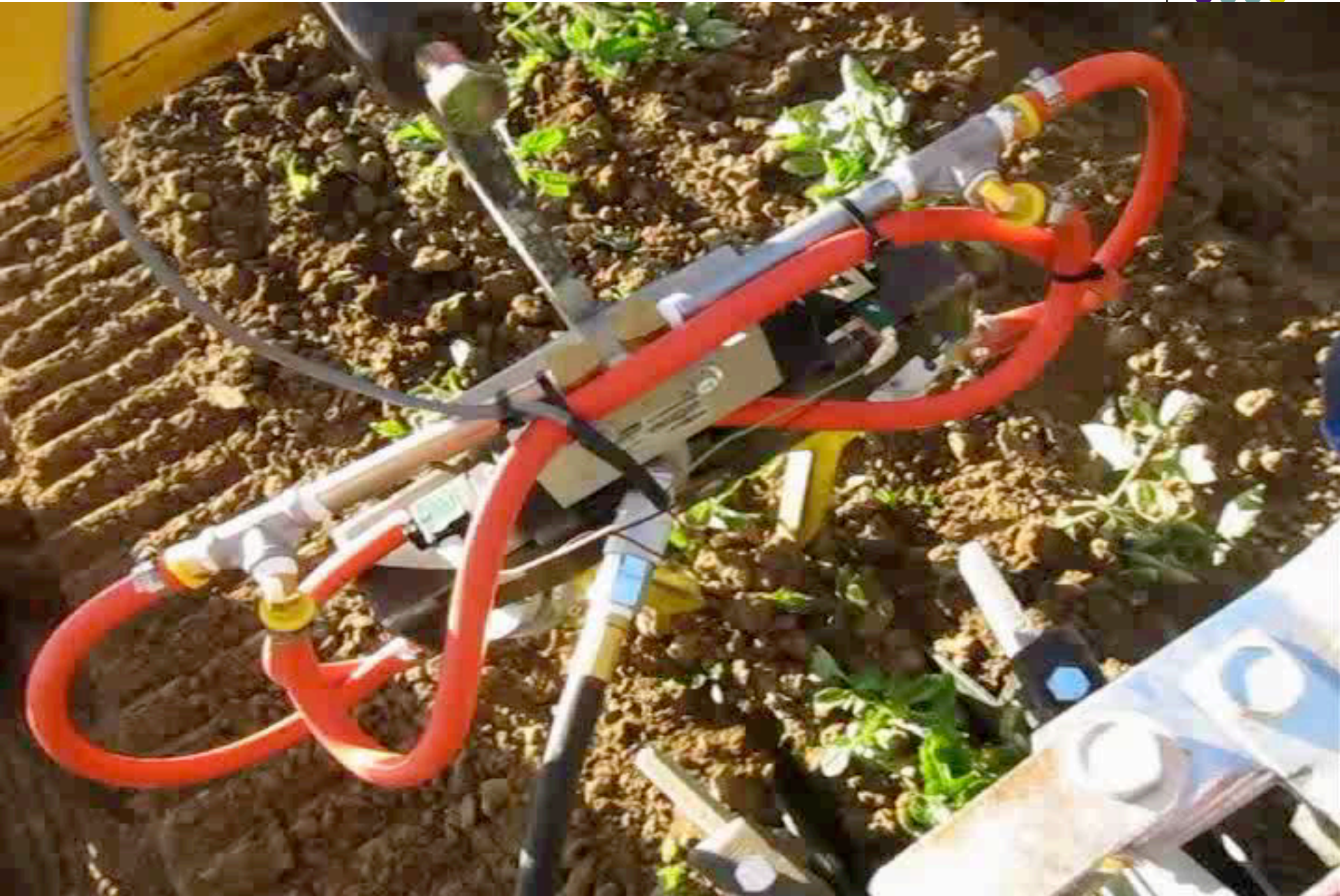
**Safety  
Zone**



# Odometry & GNSS- based mechanized weed control

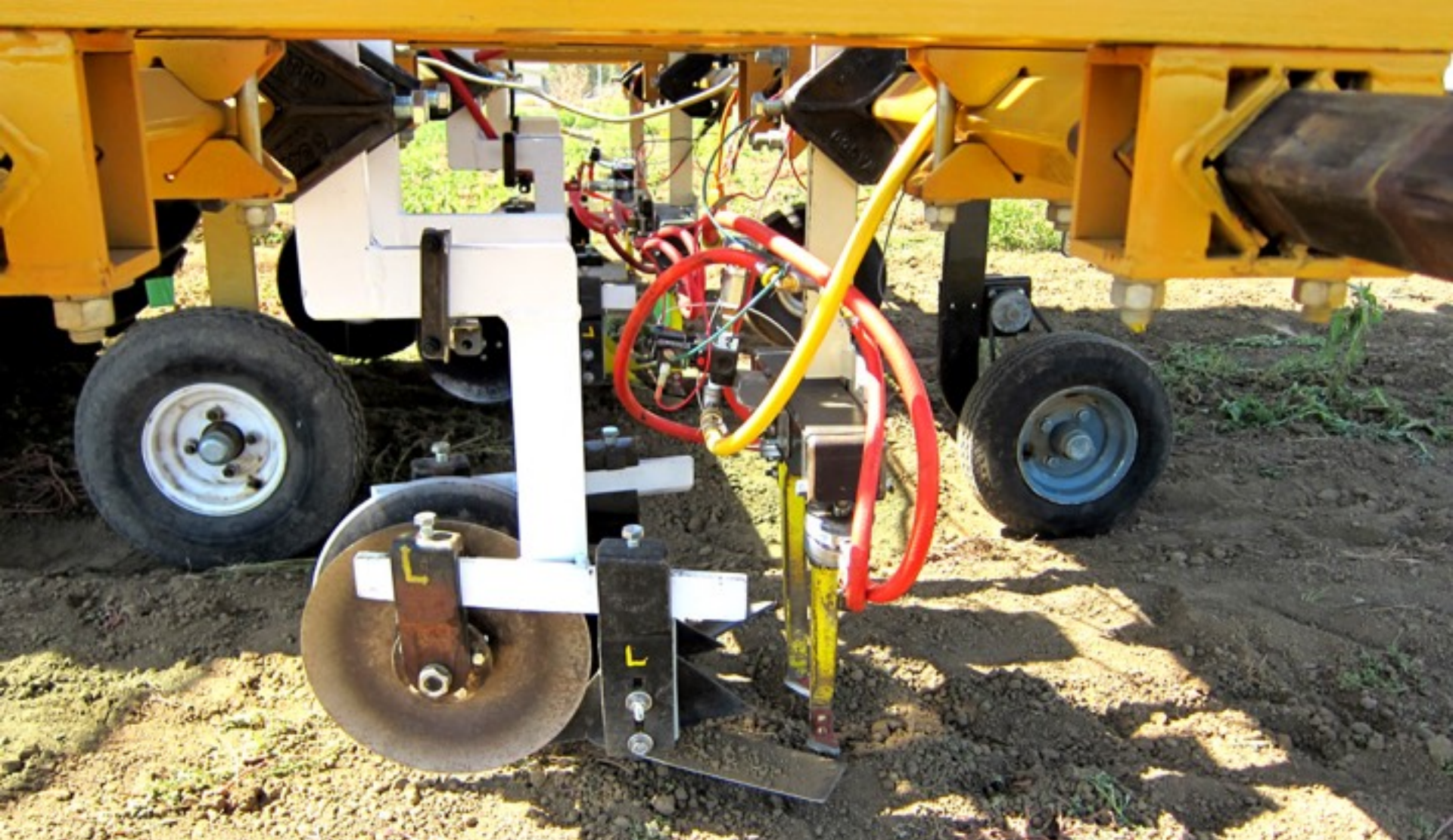


# Odometry & GNSS- based mechanized weed control



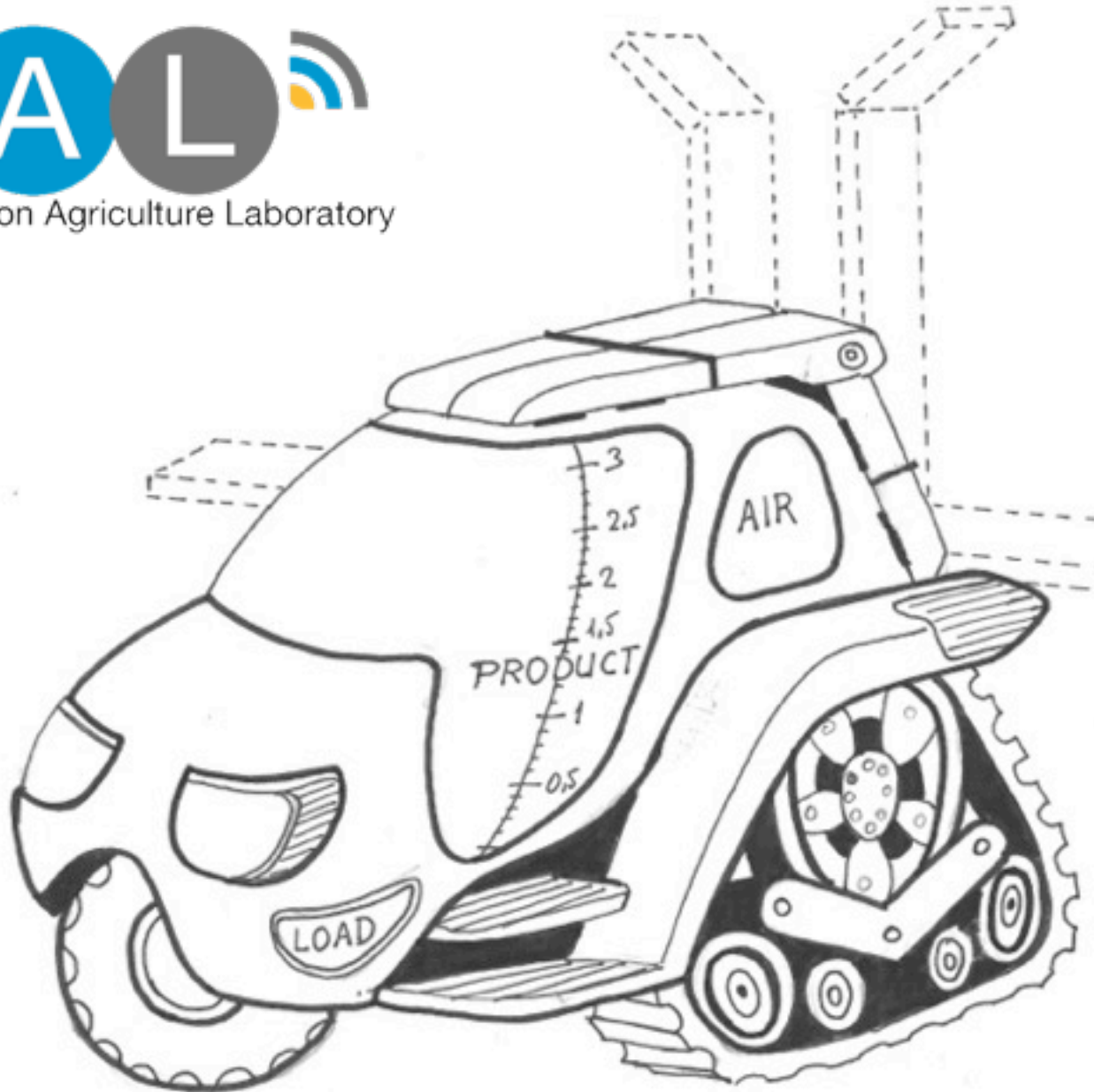
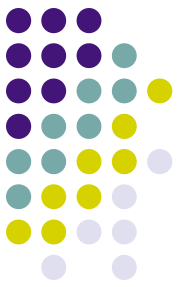


# Odometry & GNSS- based mechanized weed control

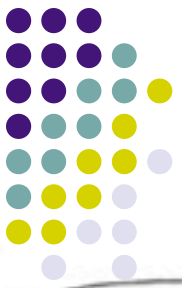




# What does the future look like????



# What does the future look like????



Precision Agriculture Laboratory

# Intelligent Weed Control Systems



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Universidad de Sevilla

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